

SYSTEM OVERVIEW

The Telesis® TMP7000/TMC600 PINSTAMP® marking system permanently prints messages into a variety of materials such as steel, aluminum, and plastic. A hardened pin is pneumatically accelerated to indent dot matrix characters into the item being marked. The shape, size, density, and location of characters are determined by the user through the system software. The marking head moves the pin cartridge through X- and Y-axis motions to reach the correct position for each dot of the characters to be marked. The system software automatically controls pin extension and retraction to mark the message.

The **TMP7000 Marking Head** includes the mechanical motion components to position the marking pin at precise X/Y positions and the pneumatic components to drive the marking pin out from, and return the pin back into, the pin cartridge.

The TMP7000 marking head is an X/Y-traversing mechanism. Using two stepper motor drives, it accurately and rapidly positions the pin at coordinate-defined locations in marking window within .001in. (.025 mm). The TMP7000 accommodates the rigorous and rapid positioning of the marking pin through a system of rigid rails and ball bearing saddles, timing belts, and direct-drive, toothed pulleys.

The floating pin design permits high quality, consistent marks on irregular, slightly curved surfaces. It also accommodates applications where marking surfaces cannot be positioned at a consistent distance from the marker.

The **Marker Cable** connects the marker to the controller. The highly flexible cable is 13 ft. (4m) long. Optional extension cables are available for greater distances.

The **Marking Pin** for the TMP7000 may be selected from the 150-series. The 150-pin is available in various cone angles and may be constructed from powdered metal or tool steel with a carbide tip. Refer to the marking head installation drawing for pin stroke (pin extension) dimensions.

The **Filter/Regulator Unit** includes two regulators with pressure gauges to control the drive air and return air. The first regulator contains a filter to help remove contaminants from the supply air. Two air lines connect the regulated air to the marking head. Drive air fires the impact pin; return air pushes it back into the cartridge. The standard air lines are 13 ft. (4m) long made of 6mm tubing.

The **TMC600 Controller** runs the MerlinTouch PS software and provides the user interface for operating the marking system. The controller features an integrated, 10-in., high-resolution, touch screen monitor in the top panel. The back panel of the controller provides the electrical interface for connecting to optional, remote I/O sources. See *TMC600 Controller Specifications* for details.

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SYSTEM SETUP

When designing a fixture, allow for 3-axis adjustment to aid in horizontal, vertical, and lateral alignment of the marking head.

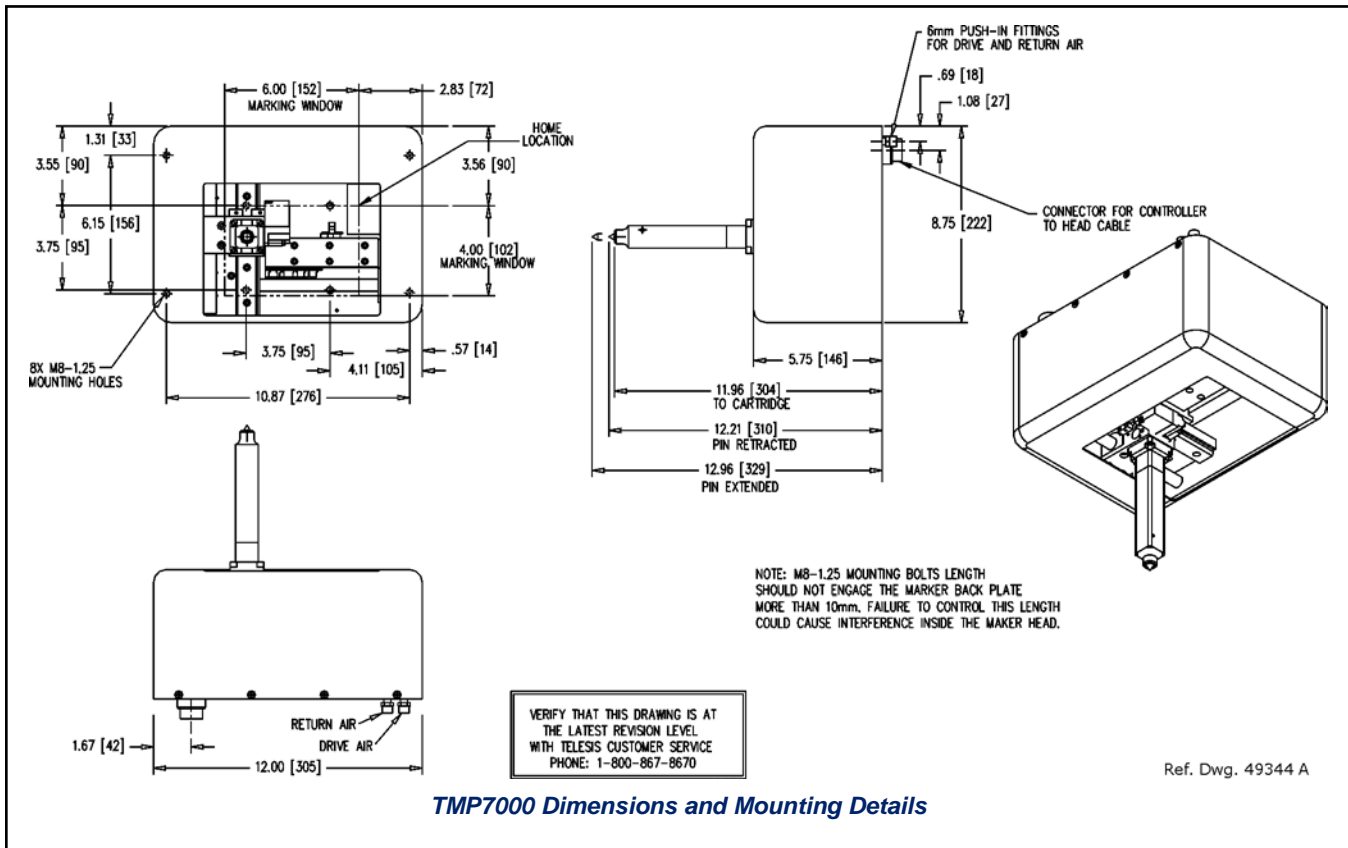
Note: Telesis recommends the marking head be mounted with the pin pointed *downward* to help prevent debris from falling into the marking head cavity.

1. Mount marking head to optional tool post assembly (or other suitable fixture) using two M6 bolts. Mounting bolts must not extend into marking head more than more 5/8" (15 mm).
2. Mount filter/regulator assembly within 12 ft. (3.6m) of marker.
3. Connect drive air and return air lines to marking head.
4. Connect supply air to input port on filter/regulator assembly.

CAUTION

The TMC600 is not a sealed unit. Protect it from potentially damaging conditions and contaminants. Do not block the vents in case. Ensure the marking system is electrically isolated from any devices that may generate extreme electromagnetic interference (EMI).

5. Install controller as a table-top unit or wall-mounted unit, as applicable. Locate controller as close as practical to marking head. Standard marker cable length is 4 m (13 ft.).
6. Ensure controller power switch is OFF.
7. Connect marker cable to controller.
8. Connect optional I/O devices to controller, as applicable.
9. Position controller power switch to ON.
10. Start marking system software.
11. Adjust pin stroke, drive air, and return air for impact depth.



TMP7000 Dimensions and Mounting Details

SYSTEM OPTIONS

- Auxiliary Axis Driver Board Kit
- Bar Code Scanner or Bar Code Wand with Cable
- Foot Switch (Start Print) or Pushbutton Station (Start/Abort)
- Marking Head Extension Cables
- Motorized Z-axis Tool Post with Programmable Travel*
- Motorized Theta-axis with Programmable Rotary Drive Unit*
- TMC600 Controller Wall-mounting Bracket Kit
- Tool Post Assembly
- USB Mouse
- USB Keyboard

* requires Auxiliary Axis Driver Board

TMP7000 MARKING HEAD

Specifications

The TMP7000 marking head specifications are subject to change without prior notice.

Dimensions.....	see <i>TMP7000 Mounting Drawing</i>
Weight	22 lb. (10Kg)
Noise	94.4 dB (max); 83.2 dB (LEQ) See <i>Marking Noise</i> for details.
Operating Temperature..	32° to 122° F (0° to 50° C), non-condensing
Air Supply	Clean and dry, 40 to 100 psi (2.8 to 6.9 bar)
Air Consumption	0.04 SCFM (idle) 0.60 SCFM (marking)
Marking Area	6.0 x 4.0 in. (150 x 100 mm)
Number of Impact Pins..	1
Pin Types.....	150-series
Pin Material.....	Powdered metal or tool steel with carbide tip

Marking Characteristics

The TMP7000 can produce characters as small as .06 in. (1.5mm), printed at any angle within the 6.0 x 4.0 in. (150 x 100 mm X/Y marking window. Character strings may be marked at any angle (0° to 359° rotation) in 1° increments. The system can also print arcs, arc text, geometric objects, and 2D matrix symbols.

Printing resolution may be selected from 10 dots/in. (4 dots/cm) to 200 dots/in. (79 dots/cm) for an engraved look.

TMP7000 MARKING HEAD (continued)

Pin Life

Pin life depends largely on the type of material being marked, how hard or abrasive it is, and the required marking depth. On typical metals with a hardness of Rockwell Rb47, marking at a depth of .127 mm (.005"), powdered steel pins average about 3 million impressions before needing sharpened; carbide pins average approximately 9 million impressions.

Marking Speeds

Marking speeds vary widely depending on character size, drive air pressure, dot density, pin stroke, and pin type. Increased character size, increased dot density, increased pin stroke, and/or decrease drive air pressure all result in decreased marking speeds. Using a carbide pin may increase marking time by as much as 25% due to the increased weight of the pin. Specific times and speeds can be verified by a Telesis representative.

Marking Depth

The depth of mark can be adjusted over a significant range by adjusting the pin stroke and, to a lesser extent, by adjusting the drive air pressure.

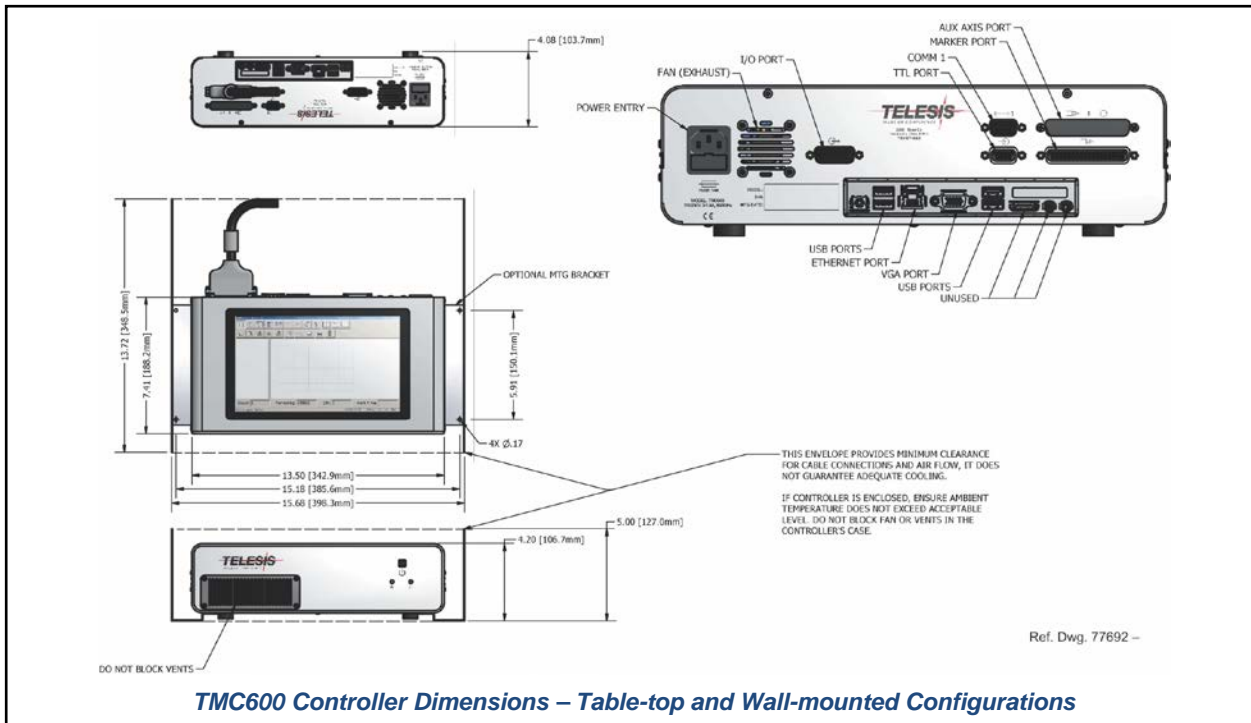
Marking Noise

Sound pressure-level tests were conducted on the TMP7000 Marking System using a Larson-Davis Model 710 sound pressure meter while dry firing the marker at a 50% duty cycle. The maximum sound pressure level during the test cycle was measured at 94.4 dB. The time-weighted average (LEQ) using the 3 db rule without threshold was 83.2 dB. Typical applications average a 20% to 30% duty cycle where the time-weighted average would not exceed 78.8 dB(A).

The sound pressure-level tests were carried out under controlled conditions, imitating as closely as possible, predicted normal operation. However, noise level is heavily dependent on the part being impacted. Conditions such as the material being marked, the rigidity of the work piece, machine settings, ambient noise, etc., may all vary when in operational use. Such variables will alter the actual noise level.

Despite detailed guidance provided with each machine, variable operating conditions are beyond the control of Telesis. The responsibility of establishing safe working levels of use remains with the end user. Accordingly, you should conduct your own sound pressure-level tests for your application while marking actual work pieces.

TMP7000/TMC600 Marking System



TMC600 Controller Dimensions – Table-top and Wall-mounted Configurations

TMC600 CONTROLLER

The TMC600 controller may be installed as a table-top unit, a wall-mounted unit, a panel-mounted unit, or an enclosure-mounted unit. All configurations provide features and connectivity for external communications. Differences occur only in the mounting configuration.

TMC600 Specifications

The TMC600 Controller specifications are subject to change without prior notice.

- Integrated Processor Intel® Dual-Core Atom™
- Integrated Monitor..... 10.1 in., color, 1024 x 600, capacitive touch screen LCD
- Compliance CE
- Rating NEMA 1 (I.P. 30)
- Configurations..... Table-top or wall-mounted
- Dimensions..... see *TMC600 Controller Dimensions* drawing
- Weight 7.00 lb. (3.18 kg) controller only
7.21 lb. (3.28 kg) with wall-mount kit
- Operating Temp. 32° to 104° F (0° to 40°C)
- Operating Humidity..... 10% to 80% non-condensing
- Power Requirements..... 115/230 VAC, 3/1.5 amps, 50/60 Hz, single phase

TMC600 Specifications (continued)

- Cooling..... Internal, thermostatically controlled fan
- Filtering..... Integrated, 60 ppi contaminant filter
- Communications ... RS232, TTL, Discrete I/O, TCP/IP, and USB (for data backup & transfer)
- Input Signals Twelve (12) total, optically isolated
8 dedicated, 1 programmable,
3 available
10 VDC minimum voltage
30 VDC maximum voltage
12 to 24 VDC nominal voltage
2.3 mA @ 12VDC nominal current
4.9 mA @ 24VDC nominal current
- Output Signals..... Six (6) total, optically isolated
3 dedicated, 3 available
0.25 amps maximum current
0.50 ohms maximum On resistance
40 VDC maximum line voltage
12 to 24 VDC nominal line voltage

Environmental Considerations

The following environmental considerations must be taken into account when installing the TMC600 Controller.

Contaminants. The vented TMC600 is rated NEMA 1 (IP30) and contains a thermostatically-controlled, variable speed fan. It also incorporates a 60 ppi filter which will filter most common contaminants. However, in certain environments, the possibility exists that contaminants can be drawn into the TMC600 controller and possibly result in failure. For that reason, in these types of environments, the controller must be located in a sealed industrial enclosure.

EMI Susceptibility. Although the system has been found to be in compliance with pertinent susceptibility standards, care should be taken when installing near welders and other extreme generators of electromagnetic interference (EMI). Particular care should be taken to ensure welder currents are not injected through the marking head chassis. The marking head chassis is connected to the electrical service earth ground through the marking head cable. The marking head should be electrically isolated from all surfaces which could become part of a welder current path.

TMC600-based System Software

The powerful Telesis MerlinTouch PS software is a Windows® based software package that comes installed in the TMC600 controller. It is a graphical user interface that makes pattern marking and pattern design quick and easy.

The WYSIWYG (what-you-see-is-what-you-get) interface provides a to-scale image of the pattern as it is created. The MerlinTouch PS software includes tools to create and edit a library of pattern files for marking. Each pattern contains one or more fields; each field defines a single object. Printable objects may be created to define text strings, arc-text strings, geometric shapes, graphics, and machine-readable data matrix symbols. Just “click and drag” for immediate adjustment to object size, location, or orientation. Note that for design purposes, Telesis recommends using a mouse for more precise use of the visual editing capabilities.

Printable text fields may include alphanumeric characters, symbols, and special message flags. Message flags automatically insert data into the text string, such as serial numbers, times, dates and user-defined codes. Multiple fields may be grouped and saved as a block to form a logo. Existing DXF files can also be imported for marking. Non-printable fields can be created to clearly display a graphical representation of the part being marked. Commands may be defined to perform specific tasks during the marking cycle (e.g., Pause, Go to, Input, or Output).

Touch Screen User Interface

The top panel of the controller contains an integrated, 10-in., high resolution, touch screen monitor. The monitor displays the MerlinTouch PS software and provides the user interface for operating the marking system.



TMC600 Controller with Touch Screen Monitor and MerlinTouch PS Software

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Interface Panel

The back panel of the controller provides various ports for connecting the marker, host computers, logic controllers, optional accessories, and remote I/O devices. See below.

RS-232 Interface. The Comm 1 port allows connection to remote serial devices such as a host computer or a bar code scanner. See *Host Communications* for details.

TTL Interface. The TTL Port allows the system to connect with a simple contact closure circuit such as a remote push button station or foot pedal switch. These types of devices can remotely control Start Print and Stop Print operations.

Discrete I/O Interface. The optically-isolated I/O Port allows you to connect a Programmable Logic Controller (PLC) or other DC I/O source for remotely controlling marker operations. See *Discrete I/O Controls* for details.

USB Interface. The USB ports allow you to connect an optional mouse and keyboard. You may also connect a memory stick/flash drive for pattern storage and retrieval and for performing software upgrades.

Ethernet Interface. The Ethernet Port may be used to connect a host computer over a local area network (LAN). It allows you to define the controller as a client or a server socket using Telesis Extended Protocol. See *Host Communications* for details.

VGA Interface. The VGA Port allows you to connect a separate VGA monitor for troubleshooting, diagnostics, and testing. Connecting a separate monitor to operate the system is not recommended since the MerlinTouch PS software is specifically designed to display on the controller's integrated, high-resolution, touch screen monitor.

(optional) Auxiliary Axis Interface. The Auxiliary Axis Port allows the system to connect with two optional motion devices such as motorized tool posts, rotational drive units, and linear slides or actuators. Note that this port is available only if the optional Auxiliary Axis Driver Board is installed in the controller.

Discrete I/O Controls

The TMC600 is configured for 12 VDC to 24 VDC I/O only and is provided to connect a PLC or other DC I/O source. The optically-isolated I/O Port allows you to remotely select and load patterns, start printing, stop printing, place the marker online, and monitor the system output signals. Cable connectors and connector pins are supplied with the controller for constructing appropriate interface cables.

Input Signals. These input signals provide the following controls:

INPUT COMM	For all inputs (+ or – supply)
START PRINT.....	Begins print cycle
STOP	Stops the print cycle
SEL_0 thru _6 *	Remotely selects & loads up to 127* patterns
SPARE_1, 2, 3	Three (3) spares for use with the Input command tool or for custom applications

* System software allows SEL_6 signal to be configured for remotely selecting patterns or for remotely placing the marker online. If used for marker online, pattern selection is reduced to 63 patterns (max).

Output Signals. These output signals indicate the following states:

OUTPUT COMM .	For all outputs (+ or – supply)
DONE	Print cycle is complete
READY	System ready for message or for start print command
PAUSED	System paused (waiting timeout or command)
SPARE_1, 2, 3	Three (3) spares for use with the Output command tool or for custom applications

Host Communications

The marking system software allows you to configure communication parameters to transmit and receive data to and from a host computer. To provide maximum integration flexibility, the system software supports RS-232 serial interfaces and Ethernet TCP/IP interfaces. The system software also provides two protocol choices: Programmable Protocol and Extended Protocol.

RS-232 Interface. The serial (RS-232) communications interface is most often used with remote devices such as host computers, terminals, or bar code scanners. The RS-232 interface supports both Telesis Extended Protocol and Telesis Programmable Protocol.

TCP/IP Interface. The Ethernet (TCP/IP) interface is most often used with host computers communicating over a local area network (LAN). You must use Telesis Extended Protocol with the TCP/IP interface.

The Port parameter identifies the host computer socket that is assigned to the marking system. If more than one marking system is installed in a network configuration, each system must use a separate and unique port number. The Address parameter identifies the IP address of the host computer. The marking system software supports both fixed addressing and dynamic addressing.

Programmable Protocol. Use this protocol where very simple one-way communications are required (such as with bar code scanners). Programmable Protocol provides no error checking or acknowledgment of the transmitted data. Note that XON/XOFF Protocol applies even when Programmable Protocol is selected.

Starting Character specifies where the software begins to count character positions. This number must be entered in decimal format (e.g., "2" for ASCII Start of Text "STX").

Terminating Character identifies the end of transmitted string (usually "13" for ASCII carriage return character).

Character Position counted from the starting character ignoring all characters preceding it.

Character Length accepts variable length messages (if set to 0) or messages of a pre-specified, fixed number of characters.

Ignore Character identifies the character to ignore when sent from the host (usually "10" for ASCII line feed character)).

Message Type allows message-type recognition which defines how the marking system will use data it receives from the host.

- 1** Message type 1 overwrites the *first line of the first text field* with data extracted from the host
- P** Message type P loads a specific pattern identified by data extracted from host
- Q** Message type Q updates the text in the *first query buffer* with data extracted from the host
- V** Message type V updates the *first variable text flag* found in the pattern with data extracted from the host
- 0** Message type 0 (zero) indicates that host will provide message type, field number (if applicable), line number (if applicable), and data; delegates message type selection to the host on message-by-message basis. The host message must use the format:

Tnn<string>

where:

- T** = 1, P, Q, or V to indicate message type
- nn** = two-digit field number or query text buffer where data will be placed.

Note: Not used with Message Type P.

<string> = For Message Type P, indicates the pattern name to be loaded.

For Message Types 1, Q, or V, indicates the data to be inserted into the field or the query text buffer, as applicable.

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Host Communications (continued)

Extended Protocol. This protocol selection includes error checking and transmission acknowledgment. It should be used in applications where serial communication is a vital part of the marking operation. All communications are carried out in a parent/child relationship with the host being the parent. Only the host has the ability to initiate communications. If the host does not receive a response within three seconds, it should re-transmit its original message. If no response is received after three tries, it should declare the link to be down.

The following describes the Extended Protocol message format as sent from the host to the TMC600 controller.

Note: Input SEL_6 may be configured to place machine online (default) or for Remote Pattern Selection.

SOH TYPE [##] STX [DATA] ETX BCC CR

where:

- SOH** ASCII Start of Header character (001H). The controller ignores all characters received prior to the SOH.
- TYPE** A single, printable ASCII character that defines the meaning (type) and content of the message downloaded from the host, where:
- 1** Message Type 1 overwrites a specific field in currently loaded pattern with data supplied in the host message. See [DATA] for details.
 - P** Message Type P specifies the pattern name to be loaded for printing. See [DATA] for details.
 - Q** Message Type Q updates a specific query buffer with data supplied in the host message. See [DATA] for details.
 - V** Message Type V updates the variable text in a specific text field of the currently loaded pattern with data supplied in the host message. See [DATA] for details.
 - O** Message Type O resets marker and places it online
 - G** Message Type G initiates a print cycle to mark the currently loaded pattern
 - I** Message Type I requests the marker return the status of standard output and input signals. The system will return a hexadecimal code for the 6 output signals and 12 input signals in the following format:

OO ; III

where:

bit 1	READY	0x01
bit 2	DONE	0x02
bit 3	PAUSED	0x04
bit 4	NO_FAULT	0x08
bit 5	SPARE_1	0x10
bit 6	SPARE_2	0x20
bit 1	START	0x001
bit 2	STOP	0x002
bit 3	SEL_0	0x004
bit 4	SEL_1	0x008
bit 5	SEL_2	0x010
bit 6	SEL_3	0x020
bit 7	SEL_6 *	0x040
bit 8	SEL_4	0x080
bit 9	SEL_5	0x100
bit 10	SPARE_1	0x200
bit 11	SPARE_2	0x400
bit 12	SPARE_3	0x800

[##] Optional two-digit ASCII number that specifies the Station ID of the controller when used in multi-drop network applications. The Station ID may range from 00-31. Note that "00" is reserved for applications where only one controller is used. In such applications, this field may be eliminated and "00" will be assumed.

STX ASCII Start of Text Character (002H).

[DATA] Optional character string that may be required for certain message types (e.g., Type 1, P, Q, and V).

Typically, data is sent in the format:

nn<string>.

where:

nn = two-digit field number or query text buffer where data will be placed.

Note: Not used with Message Type P.

<string> = For Message Type P, indicates the pattern name to be loaded.

For Message Types 1, Q, or V, indicates the data to be inserted into the field or the query text buffer, as applicable.

ETX ASCII end of text character (003H).

BCC Optional Block Check Code that is generated and sent to improve link reliability by providing fault detection. The BCC is calculated by taking an eight bit addition of the TYPE and DATA TEXT characters and transmitting them as a three digit ASCII decimal number in the range from 000 to 255. If the sum is greater than 255, the most significant bit overflows and is discarded.

CR ASCII Carriage Return Character (00DH).

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